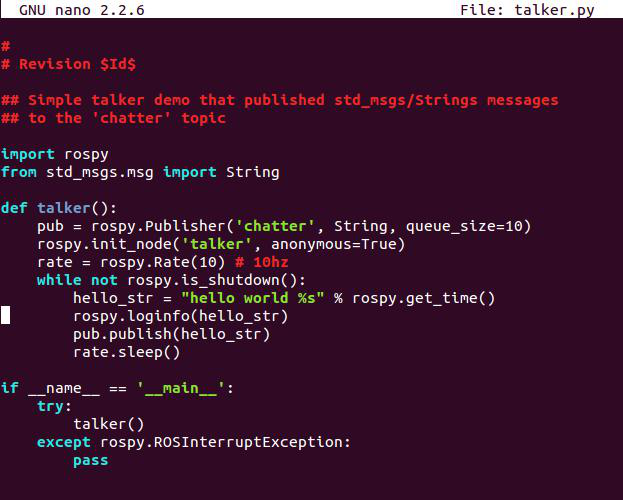
Workbook 1

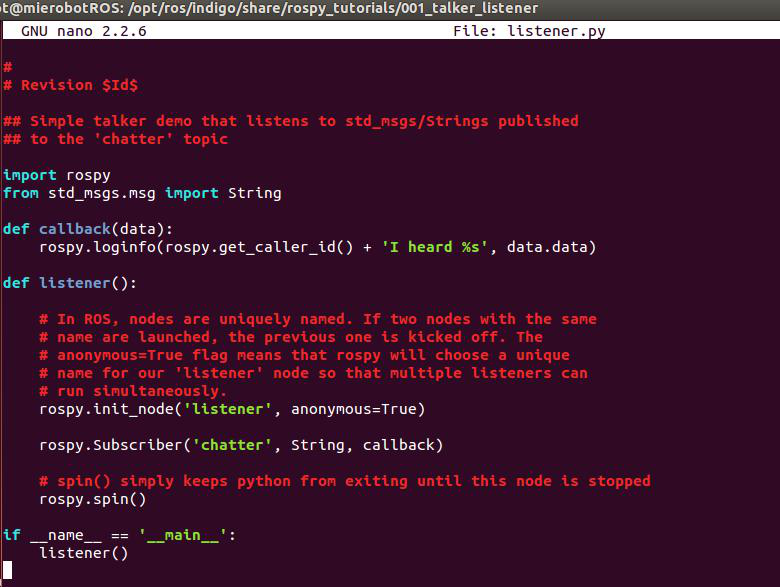
1. Run command rosrun rospy\_tutorials talker
2. rostopic list
3. rostopic echo /chatter

Exercise: Now run rosrun roscpp\_tutorials talker

Exercise: roscd rospy\_tutorials

& find the python talker file using nano editor





Exercise: Run RQT graph as below with rosrun rqt\_graph rqt\_graph

